Clothing Image Retrieval with Triplet Capsule Networks

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İstanbul, August 19th, 2019

Outline

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- Clothing Image Retrieval
- Triplet-based Similarity Learning
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- Experimental Study
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- Online shopping is a highly **growing** market.
- Global fashion e-commerce market has a volume of **480B \$**¹ .
- **Using visual information of the products** is one of the most sophisticated way to adapt developing technologies to the sales process.

¹ According to Fashion E-Commerce Report 2019 by Statista

- With the help of novel techniques combining **CV** and **DNNs**, it has become easier to achieve.
- Mostly attacked to this problem by using **CNN-based architectures**.
- However, CNNs have **some intrinsic limitations** by their nature.
- Most recently proposed architecture, Capsule Networks, **claims to overcome** these limitations.

• In this thesis, we investigate the performance of

Capsule Network architecture

on **clothing image retrieval** task.

- Main goal:
- Investigating **the SOTA research** on clothing retrieval and Capsule Networks
	- The design of **Triplet-based** version of Capsule Networks
	- More **powerful feature extraction recipe** for Capsule inputs.

• Task of retrieving a clothing image in a gallery by querying an image of the same clothes.

- In fashion domain:
	- Kiapour *et al.* (2015): learning the similarity between the images is the best way to solve cross-domain image matching.
	- Huang *et al.* (2015): creating domain-specific representations by two sub-networks that are structurally similar, yet the weights are not shared is another solution for cross-domain image matching.
	- Liu *et al.* (2016): Employing the landmark information besides to the images helps to recover pose information in the images.

- In fashion domain:
	- Corbière *et al.* (2017): Integrating textual visual information (*i.e.* bag-of-words descriptors) into weakly-supervised learning process leads to get promising results.
	- Wang *et al.* (2017): Attention-based design focuses on important regions in clothing images and diminishes the effect of the background clutter.
	- Yuan *et al.* (2017): Ensembling a set of models with different complexities in cascaded manner and applying hard sampling strategies at the same time improves the performance by a wide margin.

- In fashion domain:
	- Opitz *et al.* (2018): Exploiting the independence within ensembles improves the robustness of the feature embeddings to the sampling strategy
	- Ge *et al.* (2018): Hierarchical Triplet Loss (HTL) addresses the random sampling issue during training Triplets
	- Kim *et al.* (2018): Representing different parts of the objects on the feature embeddings with different attention masks encourages the diversity in feature representation.

• Our approach:

Employing Capsule Networks to this problem

without utilizing any side information or extra module that

recovers the pose configuration in the images.

- Inspired by *Siamese Networks*.
- 3 instances of pairs for the same feed-forward Neural Network and denoted as:

x: Anchor instance; *x ⁺*: Positive instance; *x -* : Negative instance

• Sharing the weights throughout the network.

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- 3 instances of pairs for the same feed-forward Neural Network and denoted as:

x: Anchor instance; *x ⁺*: Positive instance; *x -* : Negative instance

• Sharing the weights throughout the network.

where $f(x) \in \mathbf{R}^d$, $d(l_1, l_2)$ $L(d_1, d_2) \in \mathbf{R}$

Feature embeddings:

$$
f(x) = l
$$

$$
f(x^+) = l^+
$$

$$
f(x^-) = l^-
$$

where $f(x) \in \mathbf{R}^d$, $d(l_1, l_2)$ $L(d_1, d_2) \in \mathbf{R}$

Distance metric:

$$
d(l, l^{+}) = ||f(x) - f(x^{+})||_{2}^{2}
$$

$$
d(l, l^{-}) = ||f(x) - f(x^{-})||_{2}^{2}
$$

where $f(x) \in \mathbf{R}^d$, $d(l_1, l_2)$ $L(d_1, d_2) \in \mathbf{R}$

Triplet relationship:

$$
d(l, l^+) + \alpha < d(l, l^-)
$$

where $f(x) \in \mathbf{R}^d$, $d(l_1, l_2)$ $L(d_1, d_2) \in \mathbf{R}$

Triplet loss:

$$
L(d_1, d_2) = \sum_i [d(l_i, l_i^+) - d(l_i, l_i^-) + \alpha]
$$

• Capsule Networks are recently proposed by Sabour and Hinton *et al.* (2017), with a novel routing algorithm between Capsules.

• Capsules are basically groups of neurons.

• High dimensional information:

the existence and pose configuration.

• The output of a Capsule is routed to the next Capsule layer by

a *dynamic routing algorithm*.

• In graphics:

• In inverse graphics:

- In mathematical perspective:
	- The output of capsule $i: u_i$
	- Trainable transformation matrix : W_{ij}
	- Transformed output by coordinate frame relation

$$
\hat{u}_{j|i} = W_{ij} u_i
$$

- In mathematical perspective:
	- Initial logits : b_{ij} (*i.e.* initialized to 0)
	- Represents the log prior probability of routing the output of capsule *i* to capsule *j* in the next layer.
	- Routing softmax

$$
c_{ij} = \frac{e^{b_{ij}}}{\sum e^{b_{ij}}}
$$

- In mathematical perspective:
	- Non-activated input for capsule *j*

$$
s_j = \sum_i c_{ij} \hat{u}_{j|i}
$$

• Activation of the input for capsule *j (i.e.* squashing)

$$
v_j = \frac{\|s_j\|^2}{1 + \|s_j\|^2} \frac{s_j}{\|s_j\| + \epsilon}
$$

- In mathematical perspective:
	- Agreement between coordinate frames (*i.e.* dot product of transformed output of capsule *i* and activated input of capsule *j*)

$$
a_{ij}=v_j\hat{u}_{j|i}
$$

• Objective function:

 $L_k = T_k max(0, m^+ - ||v_k||)^2 + \lambda (1 - T_k) max(0, ||v_k|| - m^-)^2$

- Capsule Networks can **perform well** by
	- flowing **more descriptive** information between layers
	- preserving **the part-whole relationship** of the objects
- and regardless to
	- **the amount** of data
	- **the diversity** of data

- We have **3** design steps:
	- **Powerful feature extraction blocks** for Capsule inputs
	- Adjusting the original architecture to **Triplet-based design**
	- Designing **Capsule layers**

- Feature extraction blocks:
	- In default methodology, the feature extraction block has a **single** convolutional layer with **64** filters.
	- We design **two** different feature extraction blocks to generate Capsule inputs.

- **1. Stacking** several convolutional layers
	- with **different number of filters**
	- followed by **leaky-formed rectifiers** and **batch normalization**

2. Connecting stacked-convolutional layers as **residuals**

- Triplet-based design:
	- Learning **the similarity** between images
	- Feeding the objective function with **the embedded sparse representations** extracted by **Capsules**

- Capsule layers:
	- Two fully-connected Capsule layers which are called *Primary Capsule* and *Class Capsule*, respectively.

• Baseline study:

- Data set:
	- **In-shop** partition of DeepFashion
	- 25k training, 14k query and 12k gallery images

Original Landmarks Human Joints Poselets

• Data set:

• 1000 Attributes

• **At most** 8 visible Landmarks

• Implementation details:

- 2 MSI GTX 1080 Ti Armor OC 11 GB
- Framework: **Keras** with TF backend¹
- Hyper-parameter settings:

¹Source code: <https://github.com/birdortyedi/image-retrieval-with-capsules>

• Data augmentation:

• Qualitative Results:

• Qualitative Results:

• Quantitative Results:

• **Details** of architectures in the comparison:

- Quantitative Results:
	- Inner comparison:

- Quantitative Results:
	- Comparison with **the Baseline study**:

- Quantitative Results:
	- Comparison with **the SOTA**:

- Quantitative Results:
	- Comparison with **the SOTA**:

- Ablation study 1:
	- **Category-specific** comparison:

- Ablation study 2:
	- Category classification comparison:
	- with **the Baseline study**:

- Ablation study 2:
	- Category classification comparison:
	- with the **SOTA**:

Conclusion

- To the best of our knowledge, nobody attacks to
	- Any information retrieval task
	- Any fashion-related task
	- Any task using ImageNet-sized data set
	- Any task using a data set with 6-digit number of samples

by using Capsule Networks so far.

Conclusion

- In this thesis, we show that
	- Capsule Networks can be designed as **Triplet-based** to learn the similarity between the images.
	- Employing **more powerful feature extraction methods** for Capsule inputs improves the performance of Capsules significantly.

Conclusion

- In this thesis, we also show that
	- Capsule Networks **can achieve even better results** than CNN-based architectures that use different side information or extra module **to recover pose configuration** of the objects.
	- Capsule Networks can get comparable results to the SOTA architectures by using **only images** and with **only half of the parameters** in the SOTA architectures.

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Thank you!